

## Gauss-Zeidel method for solving linear systems of equations

The Gauss-Zeidel method is a modification of the iteration methods that are the same type as the method of consecutive approximations and the method of the simple iteration (Jacobi).

## Gauss-Zeidel scheme for the method of consecutive approximations:

$$x_i^{(k)} = \sum_{j=1}^{i-1} b_{ij} x_j^{(k)} + \sum_{j=i}^n b_{ij} x_j^{(k-1)} + b_i, \qquad i = 1, 2, ..., n; \qquad k = 1, 2, ..., n$$

or in an expanded form

$$\begin{vmatrix} x_1^{(k)} = b_{11}x_1^{(k-1)} + b_{12}x_2^{(k-1)} + b_{13}x_3^{(k-1)} + \dots + b_{1n-1}x_{n-1}^{(k-1)} + b_{1n}x_n^{(k-1)} + b_1 \\ x_2^{(k)} = b_{21}x_1^{(k)} + b_{22}x_2^{(k-1)} + b_{23}x_3^{(k-1)} + \dots + b_{2n-1}x_{n-1}^{(k-1)} + b_{2n}x_n^{(k-1)} + b_2 \\ x_3^{(k)} = b_{31}x_1^{(k)} + b_{32}x_2^{(k)} + b_{33}x_3^{(k-1)} + \dots + b_{3n-1}x_{n-1}^{(k-1)} + b_{3n}x_n^{(k-1)} + b_3 \\ \dots \\ x_n^{(k)} = b_{n1}x_1^{(k)} + b_{n2}x_2^{(k)} + b_{n3}x_3^{(k)} + \dots + b_{nn-1}x_{n-1}^{(k)} + b_{nn}x_n^{(k-1)} + b_n \\ k = 1, 2, \dots \end{aligned}$$

## Gauss-Zeidel scheme for the method of simple iteration:

$$x_i^{(k)} = \sum_{j=1}^{i-1} c_{ij} x_j^{(k)} + \sum_{j=i}^n c_{ij} x_j^{(k-1)} + d_i, \qquad i = 1, 2, \dots, n; \qquad k = 1, 2, \dots$$

In this case the expanded form is the same as the previous one. In both methods the Gauss-Zeidel modification is subject to the following scheme for finding a  $k^{th}$  approximation:

$$\fbox{x_1^{(k)}} \quad , \quad \fbox{x_2^{(k)}} \quad , \quad \fbox{x_3^{(k)}} \quad , \dots, \quad \fbox{x_{n-1}^{(k)}} \quad , \quad x_n^{(k-1)} \quad \rightarrow \quad x_n^{(k)}$$

The conditions for convergence of the method of consecutive approximations and the Jacobi method are **sufficient conditions** for the convergence of the Zeidel modification. In most cases the Zeidel modification is faster, but not in order:

The Gauss-Zeidel modification can converge when the Jacobi method and the method of consecutive approximations are not.

**Example.** For the given system apply the Gauss-Zeidel modification for the Jacobi method. Work with an accuracy of six digits after the decimal point, using the zero vector as initial guess. Make six iterations.

$$\begin{array}{rcl}
4x_1 & -x_2 & = 2 \\
-x_1 & +4x_2 & -x_3 & = 6 \\
& & -x_2 & +4x_3 & = 2
\end{array}$$

## Solution:

$$\boxed{1.} \quad A = \begin{pmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 4 \end{pmatrix} \quad \rightarrow \quad C = \begin{pmatrix} 0 & 0,25 & 0 \\ 0,25 & 0 & 0,25 \\ 0 & 0,25 & 0 \end{pmatrix}; \quad b = \begin{pmatrix} 2 \\ 6 \\ 2 \end{pmatrix} \rightarrow \quad d = \begin{pmatrix} 0,5 \\ 1,5 \\ 0,5 \end{pmatrix}.$$

2.

Convergence check – done (see the same example in the theme Jacobi Method). Execution of six iterations:

$$\begin{array}{rcl} x_1^{(2)} = & 0,25x_2^{(1)} & +0,5 = & 0,25.(1,625) + 0,5 = 0,90625 \\ x_2^{(2)} = & 0,25x_1^{(2)} & +0,25x_3^{(1)} & +1,5 = 0,25.(0,90625) + 0,25.(0,90625) + 1,5 = 1,953125 \\ x_3^{(2)} = & 0,25x_2^{(2)} & +0,5 = & 0,25.(1,953125) + 0,5 = 0,988281 \end{array}$$

$$\rightarrow \begin{array}{c} x_1^{(2)} = 0,90625 \\ x_2^{(2)} = 1,953125 \\ x_3^{(2)} = 0,988281 \end{array}.$$

Do the other iterations independently. The results are printed in the following table. Do one more thing: compare these results with the results of table 2 in the theme Jacobi method and make your conclusion.

Table 3

x <sup>(k)</sup> k	$x_1^{(k)}$	$x_{2}^{(k)}$	$x_{3}^{(k)}$
0	0	0	0
1	0,5	1,625	0,90625
2	0,90625	1,953125	0,988281
3	0,988281	1,994141	0,998535
4	0,998535	1,999268	0,999817
5	0,999817	1,999908	0,999977
6	0,999977	1,999989	0,999997
x*	1	2	1

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